


The background features four large, stylized geometric shapes in the corners, each with a dark grey outer border and a white inner border. The top-left and bottom-right shapes are dark grey, while the top-right and bottom-left shapes are light grey. All shapes are oriented towards the center of the page.

Better Together

V Nguyen, OTD, OTR/L
v@hello-robot.com

A romantic couple is shown in profile, about to kiss. The man is on the left, and the woman is on the right. A speech bubble from the man contains a pun. The background is dark and out of focus.

I'm an
Occupational
Therapist

You lost me
at Occupation

@WTF_is_OT

What's Occupational Therapy?

“Occupational Therapy? Never heard of it.”

“OT seems just like PT”

“Anyway, I don't really need help getting a job”



Interdisciplinary from the Start



The founders of occupational therapy at Clifton Springs Sanitorium in 1917.

Back row (from left):

- William Rush Dunton - psychiatrist
- Isabel Newton - *secretary*
- Thomas Bessell Kidner - *architect*

Front row (from left):

- Susan Cox Johnson - *teacher*
- George Edward Barton – *architect and patient (tuberculosis)*
- Eleanor Clarke Slagle - *social welfare reformer*

Not shown:

- Susan Tracy - *nurse*



Interdisciplinary Team



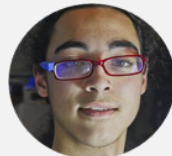
Summer 2021 Team



Vy Nguyen



Maya Cakmak



Kavi Dey



Tapo Bhattacharjee



Henry & Jane Evans



Wendy Rogers



Harshal Mahajan



Travis Kadylak



Megan Bayles



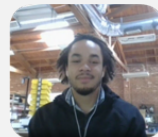
Leo Galoso



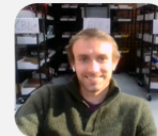
Aaron Edsinger



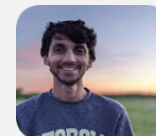
Charlie Kemp



Elliston Franks



Blaine Matulevich



Binit Shah



Aaron Edsinger
CEO



Charlie Kemp
CTO



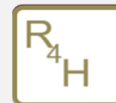
Binit Shah
Software Lead



Blaine Matulevich
Engineering



Mohamed Fazil
Robotics Software
Engineer



Henry and Jane Evans
Robots for Humanity



V Nguyen
OT Clinical
Research Lead



Anna Garverick
Robotic Applications
Engineering Intern



Alan G. Sanchez
Robotics Engineer
Intern



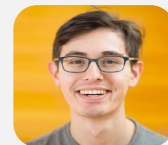
Chintan Desai
Software Development
Intern

hello robot™



Maya Cakmak
Associate
Professor of
Computer Science

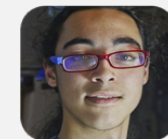
Graduate Research Assistants



Nick Walker



Research Interns



Kavi Dey



Brian Yao

Summer 2022 Team



Wendy Rogers
Khan Professor
of Applied
Health Sciences



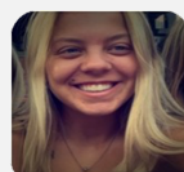
Harshal Mahajan
Assistant Director
of Research at
LIFE Home



Samuel Olatunji
Postdoctoral
Research
Associate



Megan Bayles
Graduate Research
Assistant



Megan Bily
Undergraduate
Research Assistant



UNIVERSITY OF
ILLINOIS
URBANA-CHAMPAIGN



Joe Sluis





Participatory Design



Dynamic Duo



Courtesy of the Evans Family

Henry Evans



Courtesy of the Evans Family

Age: 60

Height: 6"4

Race: White

Sex: Male

Language(s): English

Glasses: Yes

Medical Condition: Basilar Artery Dissection;
brainstem stroke; quadriplegia; non-speaking

Abilities: Cognition & sensation intact, slight left thumb
flexion; functional neck mobility; expert robotics' user

Level of Assistance: Dependent in all activities of daily
living (ADL) and majority of his instrumental ADL (IADL)

Technology Use: Computer, head tracker, mouse,
telepresence robots, AutoBed

Roles: Family man, loving husband, advocate, car
enthusiast, international speaker

Occupations: Playing cards, writing songs,
socialization, watching YouTube, working, going outside

Jane Evans



Courtesy of the Evans Family

Age: 59

Height: 5'3

Race: Peruvian, German, Chinese

Sex: Female

Language(s): English, French

Glasses: Yes

Abilities: Letter board master, super-human

Level of Assistance: Independent

Roles: Extraordinary mother, wife, and care partner; advocate; speaker

Technology use: Smart Phone, Alexa, computers, some robotics

Occupations: Cooking, hiking, reading, writing, fishing

Needs Assessment

hello robot™

Explore use cases of Stretch in Henry and Jane's home to gain feedback on improving hardware and software of Stretch.



For Henry to perform his activities of daily living more independently using Stretch and how this may relieve Jane's care partner demands.

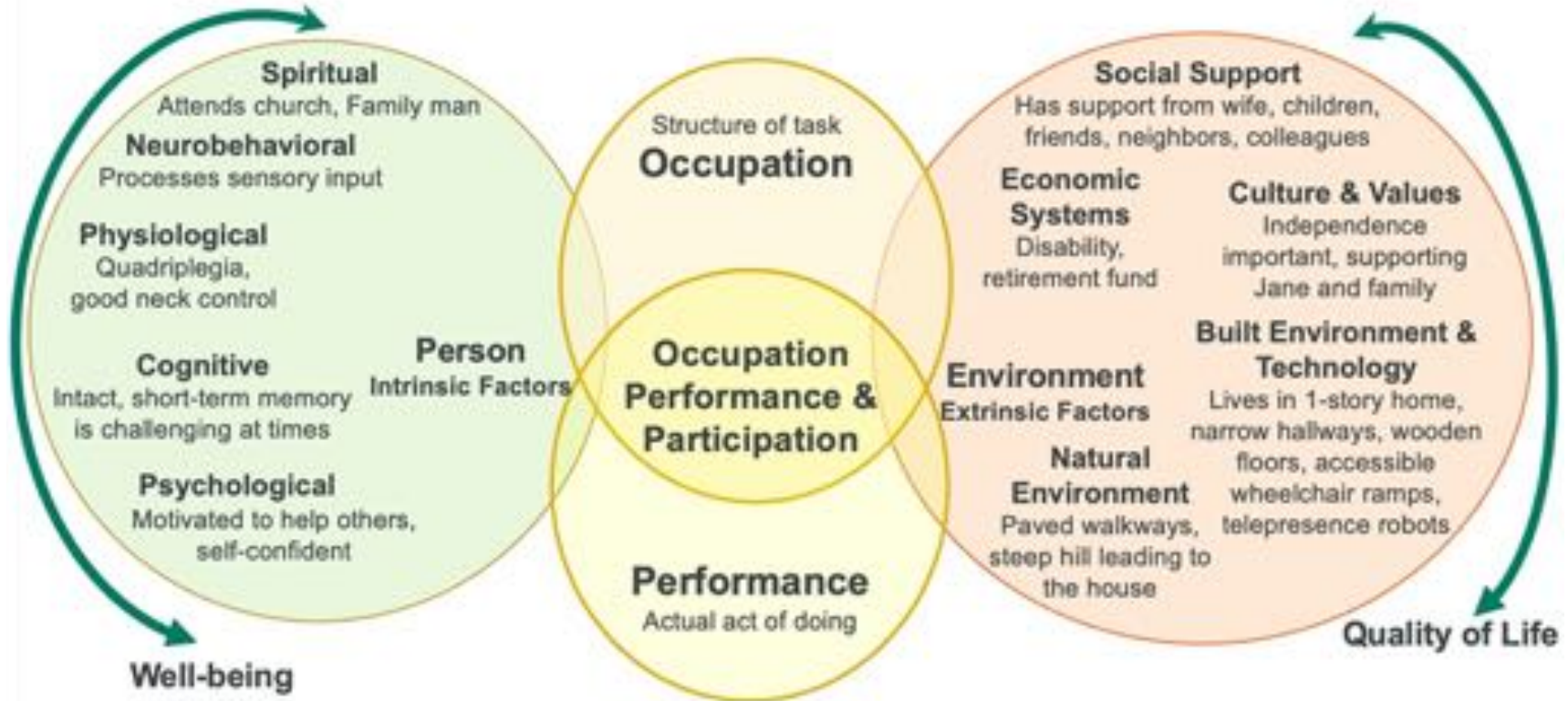


Access users who can benefit from Stretch and to get their feedback on what's most valuable to them to develop technology that is useful to people.

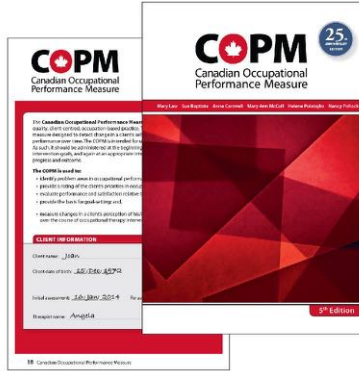


Identify the capabilities and limitations of Stretch by creating tools to make it more useful, user-centered, and beneficial in a home environment.

Person-Environment-Occupation-Performance (PEOP) Model



User-Centered Assessments



Canadian Occupational
Therapy Measure
(COPM)



NASA Task Load Index



Trust Questionnaire



Perceived Ease of Use

GAS 5-Point Rating Scale	
Score	Predicted Attainment
-2	Much less than expected outcome
-1	Less than expected outcome
0	Expected outcome after intervention
+1	Greater than expected outcome
+2	Much greater than expected outcome

Fig. 1. Scaled Levels of GAS (McDougall & King, 2007, p. 4)

Goal Attainment Scaling



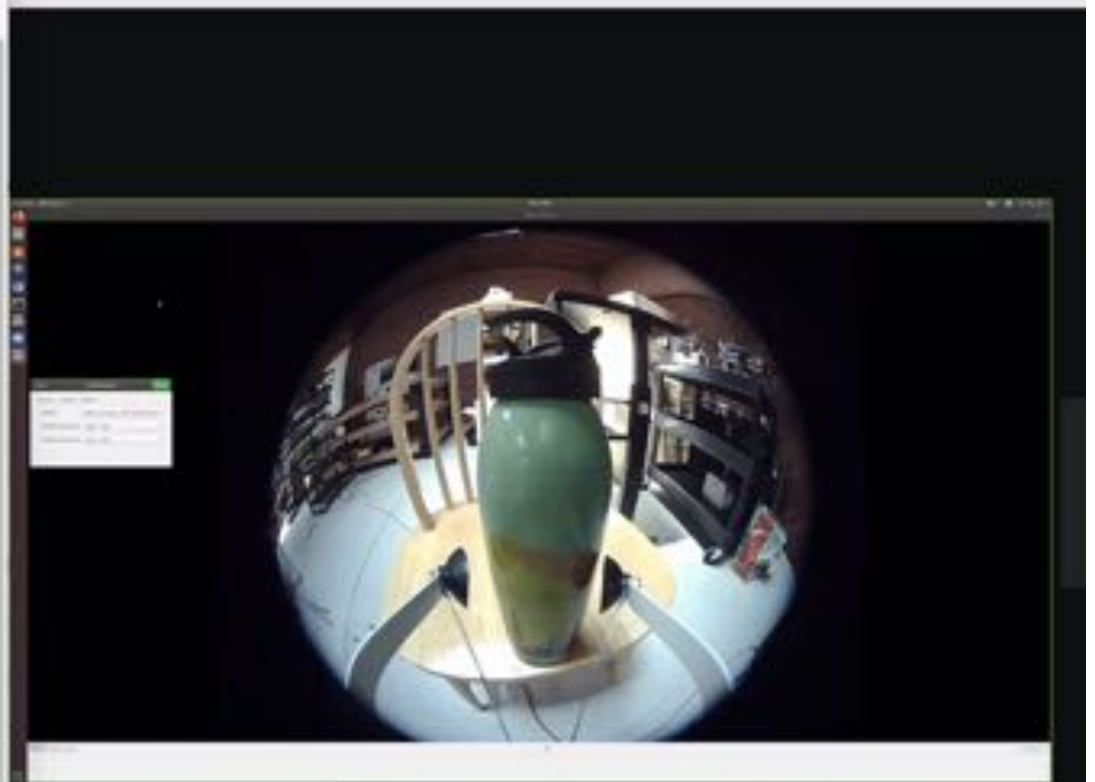
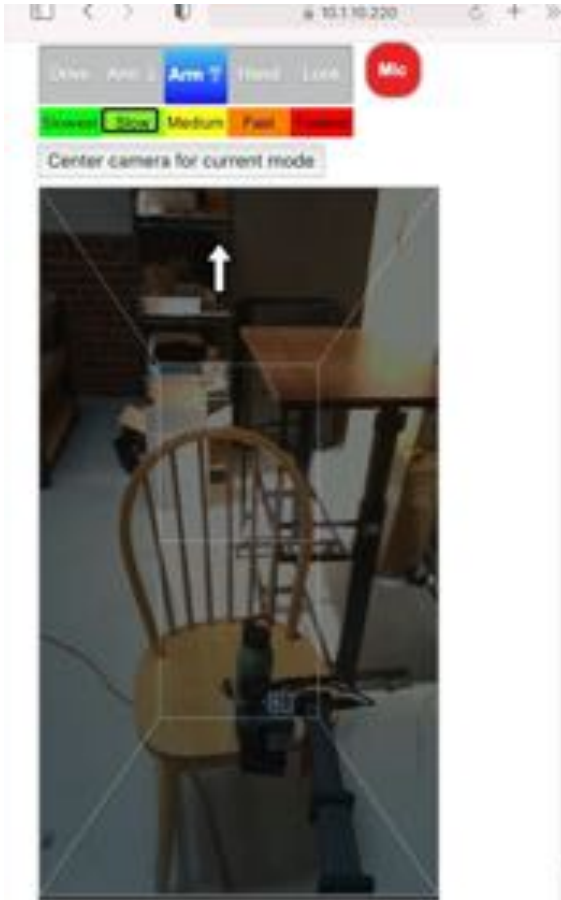
Evaluating Stretch's
Customized Settings



Iterative Process



Summer 2021



12x Teleoperated

STRETCH CONTROLS

Slowest

Slow

Medium

Fast

Fastest

Labels On/Off



Labels On/Off

Camera Controls



Navigate

Manipulate

Prepare Arm

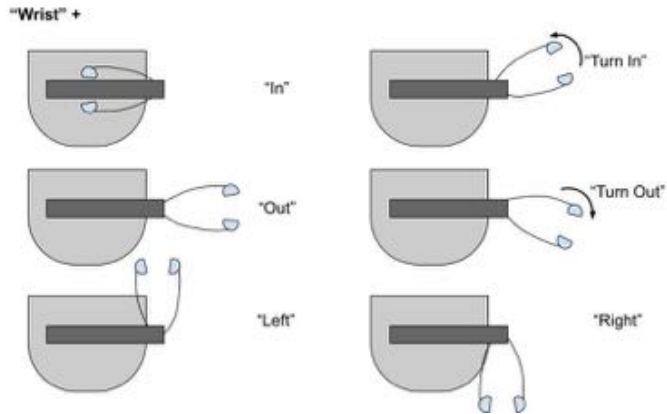
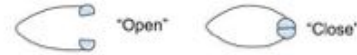
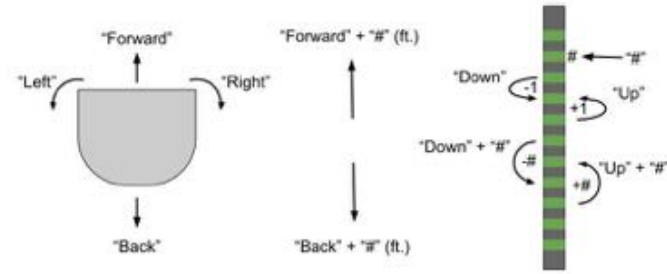
Slow Arm

Start Recording
Volume: 100% | Mute: [X] | Audio in: [Microphone 1] | Audio out: [Speakers 1]

Summer 2022

The image displays a web-based interface for controlling a robot. At the top, there is a navigation bar with 'Manipulation' selected and a 'Battery: 12.64v' indicator. Below this, the 'Action Mode' is set to 'Press-Release' and the 'Selected Action' is 'extend arm'. A speed control bar at the top right shows 'Slowest', 'Slow', 'Medium' (highlighted), 'Fast', and 'Fastest'. The main area contains three camera views: a 3D model of the robot's gripper, a top-down camera view of the gripper, and a circular fisheye camera view. To the right is a control panel with buttons for 'Slow', 'Camera', 'Wrist', and 'Arm', and a directional pad. At the bottom, there are buttons for 'Save pose', 'STOP', 'Play', and a 'Hang up' button.

Voice Commands



This is an illustration of the Voice Commands for Stretch

Making Suggestions



Adding Visual/Tactile Cues



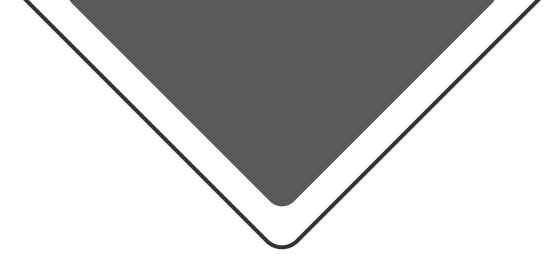
What do the tape strips mean?

- Say '#' = Stretch's arm will go to that number
- Examples:
 - > Say '1' = Stretch's arm goes to it's lowest
 - > Say '10' = Stretch's arm goes to it's highest



Tasks Performed





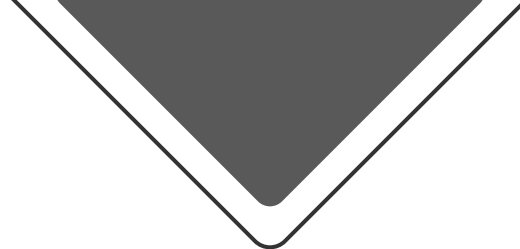
Self-feeding





Tools

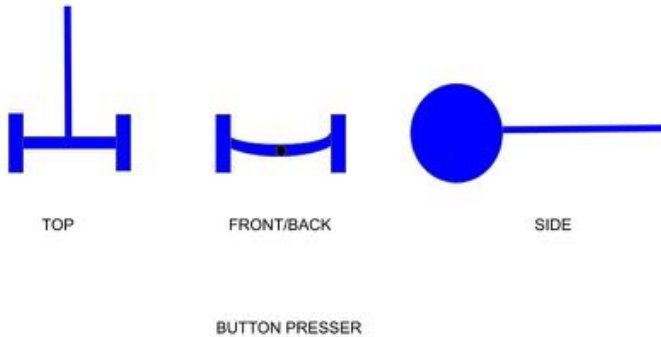




Percussion Vest Machine

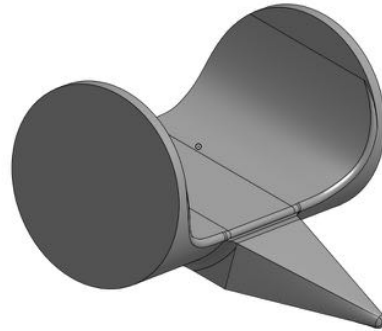


Design Process of Button Pushing Tool



1. Henry's Design

Henry created the above design using Google Slides. The tool has a curve in the middle to ensure the gripper camera has a clear view of the button on the percussion machine.



2. Anna brings The Design to Life

Anna used computer-aided design (CAD) to create a 3D printed version of the Henry's design.



3. 3D Printed Tool

Above is the final product! The tip is highlighted with green tape. The two supports on the side of the tool prevents it from sliding from the original angle optimal for pushing the button.





Stretchercise

Home Page



Jane selects her desired exercise from this 'Home Page.'
This 'Home Page' pops up whenever she is finished with an exercise.



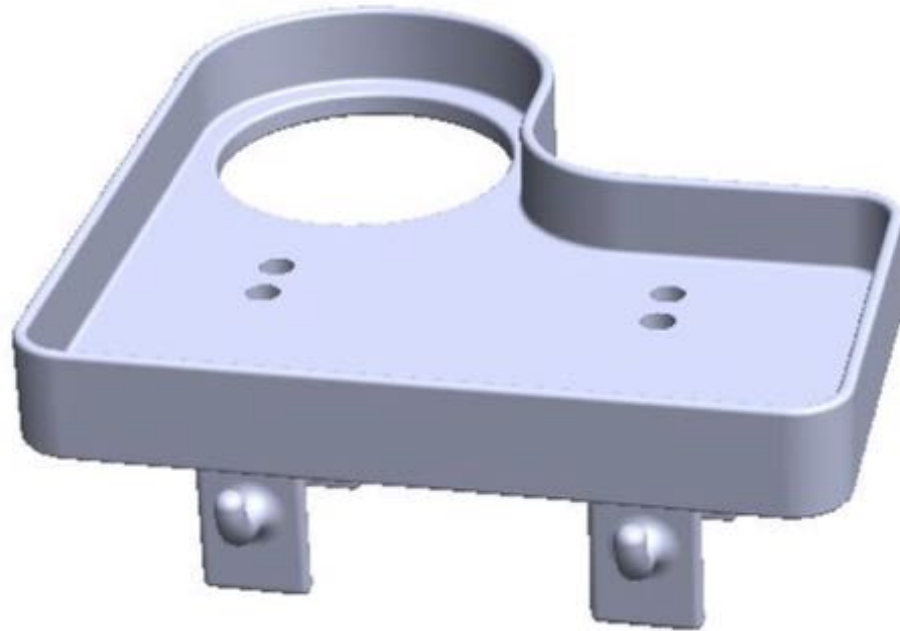






Meal Delivery
&
Clean Up

Arm-Mounted Tray



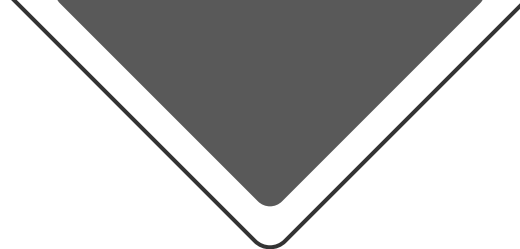










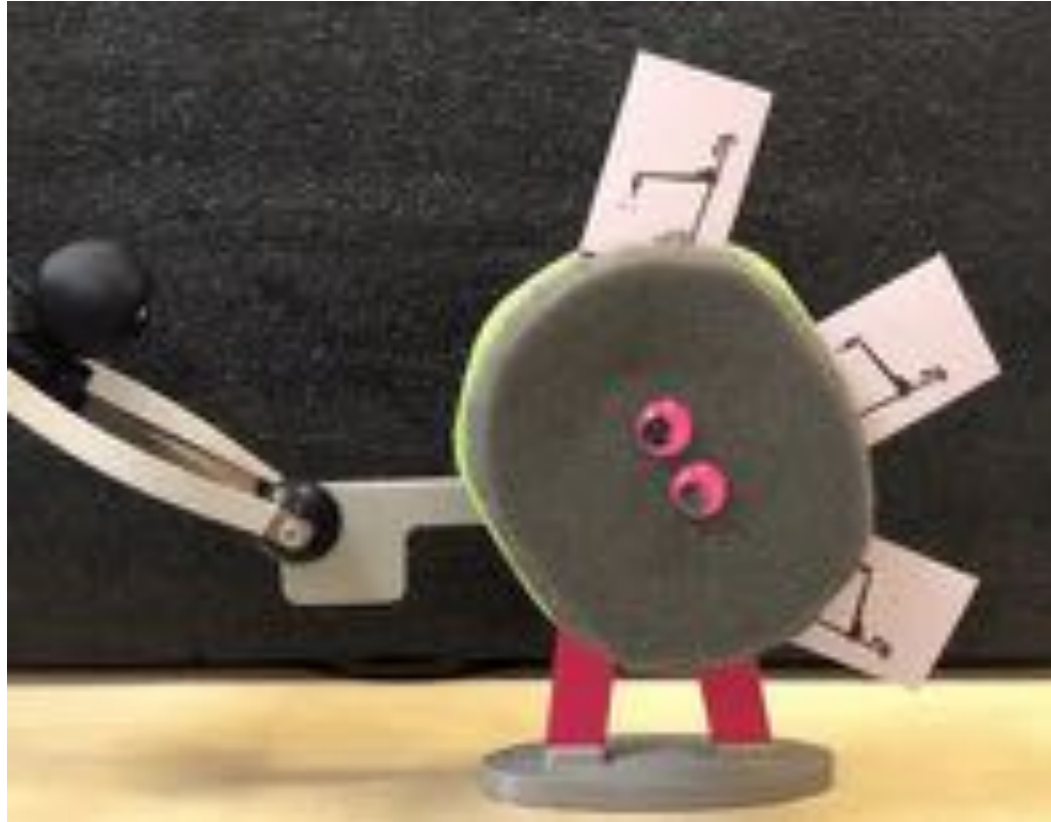


Playing Card Games

Summer 2021 Tool



Summer 2022 Tool



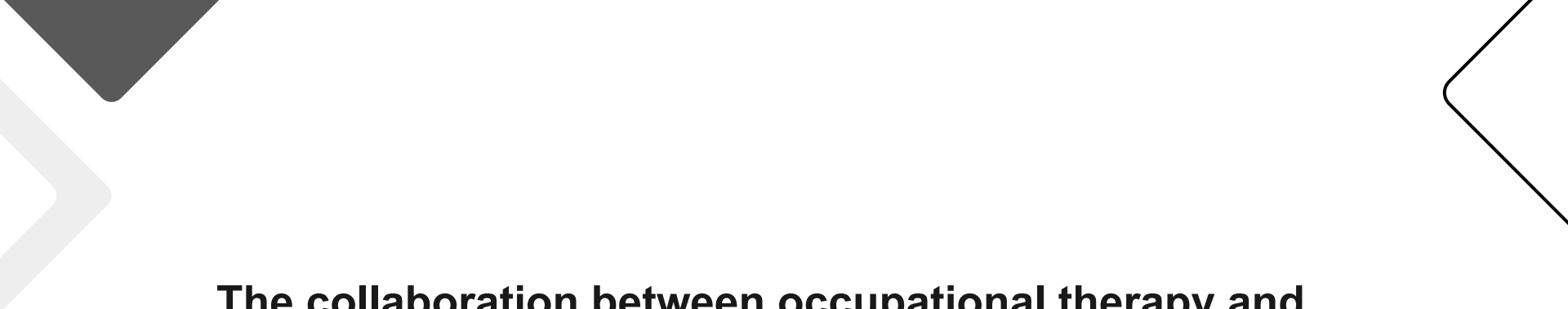
A Happy Straight in Poker





Access to Care





The collaboration between occupational therapy and engineering can bring complementary perspectives together to create technology that makes a pinnacle impact to a person, their communities, and in everyday society.

Thank you!

